

Priority queue (PQ): needs 3 operations

1. Insert a new item
2. Remove max-priority item
3. Get max-priority item (without removing) (peek)

How do we build one from scratch?

Some data structure: arrays, lists, trees, hash maps/dictionary, hash sets/set, graphs

How might you use these? Which ones might be best?

HashSets/set

=> Not really a way to specify priority

HashMap/dict

- ① Key = priority, Value = item
 - ② Key = item, Value = priority
- We could implement a heap using one of these options, but we would need to search the whole map $O(N)$

Linked list

keep a sorted list

Array list

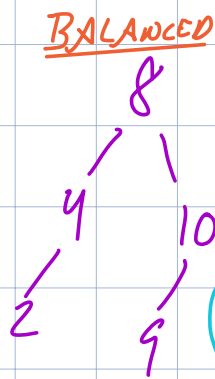
- get-max: $O(1)$ (pick first element)
- remove-max: $O(1)$ for linked list, for array list would need to shift elements to keep sorted order => $O(N)$
- insert: $O(N)$ to find position in sorted list

Trees

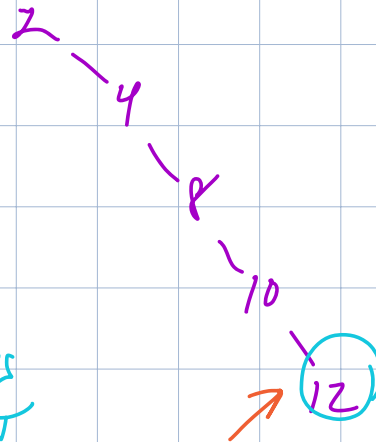
We know one way to do an ordered representation with trees...

=> BST (Binary search tree): for any node, every smaller node is on the left, any larger node is on the right

What if we used this as a priority queue?



UNBALANCED



insert, get-max :
 $O(\log N)$ if balanced
 $O(N)$ if unbalanced

MAX NODE ALWAYS AT BOTTOM-RIGHT

PROBLEMATIC IF BST IS UNBALANCED

What if we relax the rules a bit?

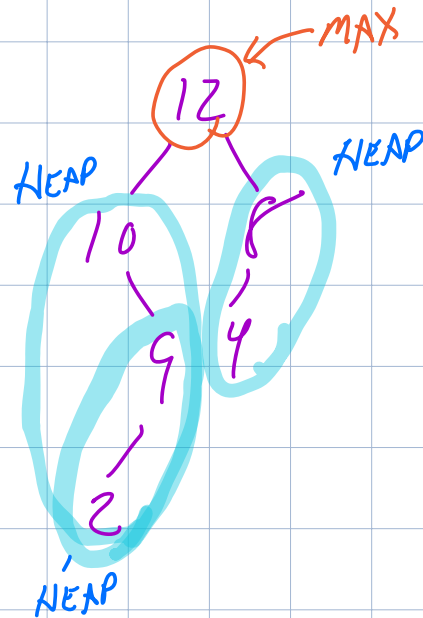
=> For a priority queue, we don't need a total order like a BST.

What if we just keep the max item at the top??

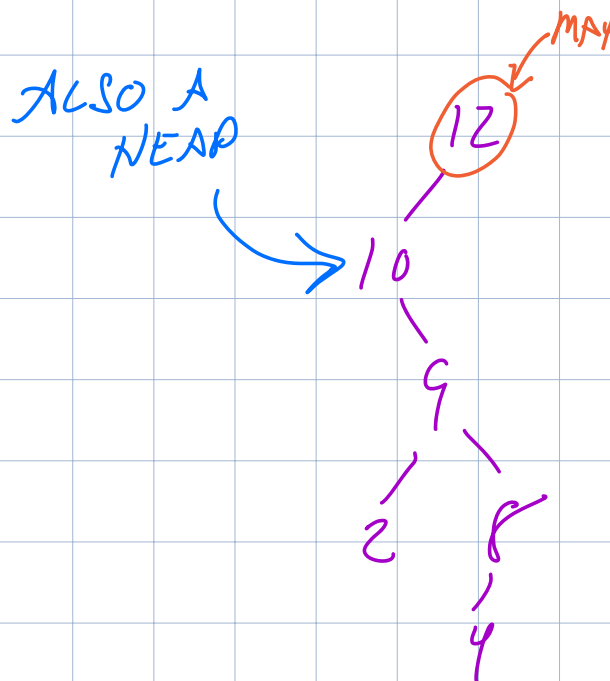
Heap (binary max heap): a binary tree (NOT a BST) with two constraints:

- max item is at the root
- left and right subtrees are also heaps

DATA: 2, 4, 8, 9, 10, 12



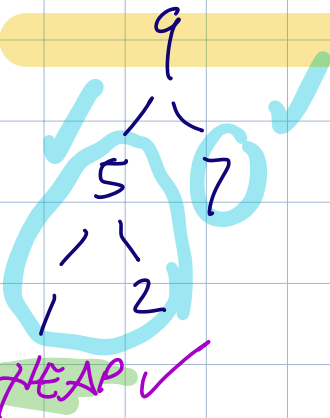
Note: can have different valid representations for the same heap
(may be more or less-balanced... more on this later)



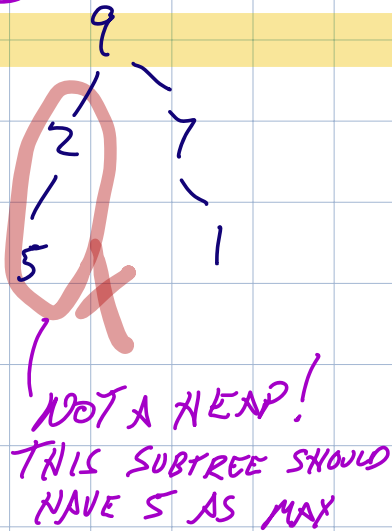
Example: which of these are heaps?

DATA: [1, 2, 5, 7, 9]

(A)



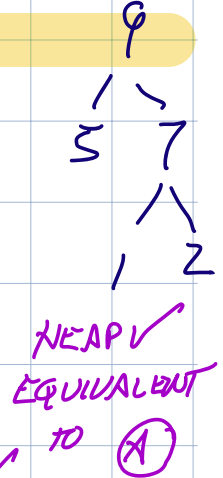
(B)



(C)



(D)



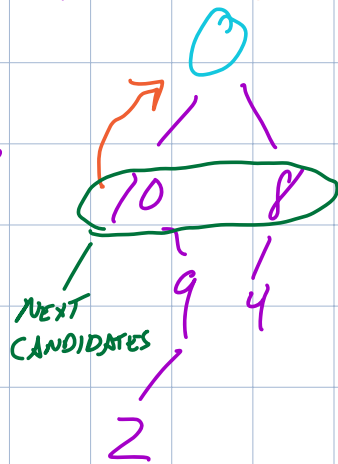
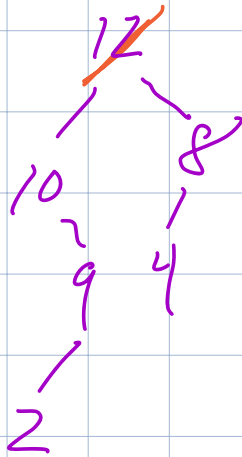
Checking in on our priority queue goals: what can we infer about the runtime of using a heap for a PQ?

Priority queue (PQ): needs 3 operations

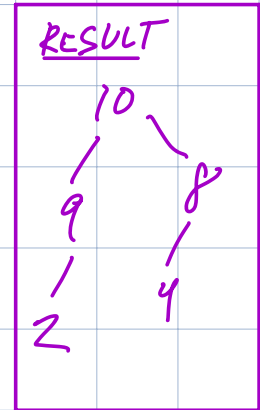
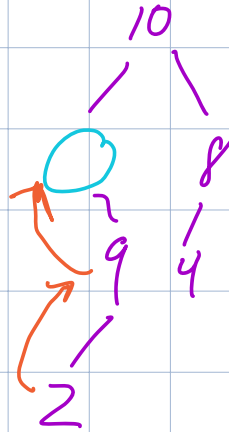
1. Insert a new item => ???
2. Remove max-priority item => ???
3. Get max-priority item (without removing)
=> $O(1)$ => can just look at top of heap!

What about add and remove?

EX. REMOVE 12



"HOLE" FROM REMOVING 12

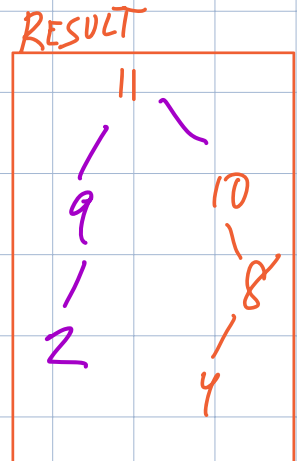
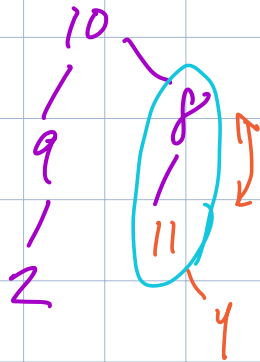


Removing an element creates a "hole", can reorder subtree to fill it

To reorder, we only need to consider one "branch" of the heap => If heap is balanced, this takes $O(\log N)$

WHAT IF WE WANT TO INSERT 11?

Strategy: add to bottom, reorder until we have a heap again



Again, we only need to reorder one "branch" of the heap => $O(\log N)$

So to SUMMARIZE...

Priority queue (PQ): needs 3 operations

if heap is balanced:

1. Insert a new item $\Rightarrow O(\log N)$
2. Remove max-priority item $\Rightarrow O(\log N)$
3. Get max-priority item (without removing)
 $\Rightarrow O(1)$

If heap is unbalanced, the insert/delete steps are harder:

- insert: $O(N)$
- remove_max: $O(N)$
- get_max: $O(1)$

Open questions (for next time):

- How to find an empty spot to insert?
- How to keep the heap balanced to ensure $\log N$ runtime?
- What does "balanced" even mean, anyway?